AutoConduct: a novel dataset for invehicle driver posture monitoring

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Outline

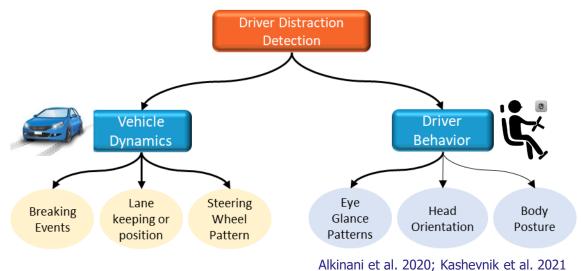
- > Introduction
- > **Objectives**
- > AutoConduct dataset
- > Posture estimation
- > Future work

Introduction

Driver distraction and road traffic safety

- ◆ Fact: 10 16 % of fatal traffic accidents are caused by distracted driving (Née et al., 2019)
- ✤ Ironies of automation: driver distraction increases with automation level (Lu et al., 2016)

Detection of driver distraction



Research on driver posture monitoring is falling behind

Introduction

In-vehicle driver posture monitoring

A challenging task due to

- Body close to vehicle interior
- Suboptimal camera placement
- Illumination, occlusions
- Accuracy requirement

Limitations of existing systems

- Incomplete body coverage (head or hands)
- 3D pose estimation rarely investigated
- Insufficient investigations of supplementary methods
- Limited validation

A critical issue

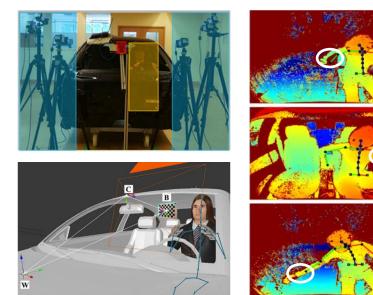
- Lack of in-vehicle driver posture datasets
 - Measurement: images, etc
 - Annotations: segmentations, joint centers, etc



Yuen and Trivedi. (2018)



Pan et al. (2021)



InCar (Borges et al. 2021)

Researchers are still struggling to find more useful data and better algorithms for driver posture monitoring



> To create an in-vehicle driver posture dataset in order to facilitate the research on driver posture monitoring

To propose more reliable driver posture estimation methods

AutoConduct dataset

Data collection and data processing

Twenty-three Drivers (11 females)

- Age: 22 65 years
- Height: 153 195 cm
- BMI: 18.2 43.4 kg/m²

42 in-vehicle tasks

- Driving tasks
- Non-driving related tasks

Motion capture system

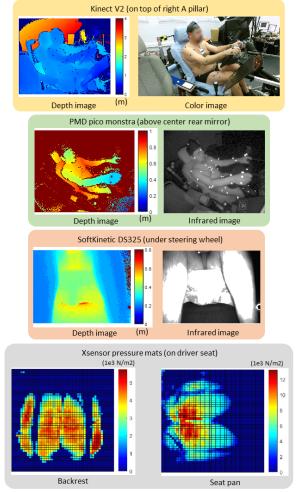
- 14 VICON cameras
- 78 reflective markers

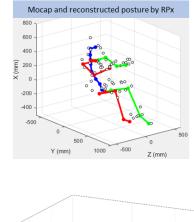
Monitoring system

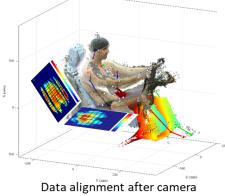
- Kinect V2
- PMD pico monstra
- SoftKinetic DS325
- 2 Xsensor pressure mats

Nature of data content (~2 hours recording)

- Anthropometry measurement
- Motion capture data (50 fps)
- Depth image flow (25 fps)
- Color image flow (25 fps)
- Infrared image flow (25 fps)
- Pressure distribution (25 fps)



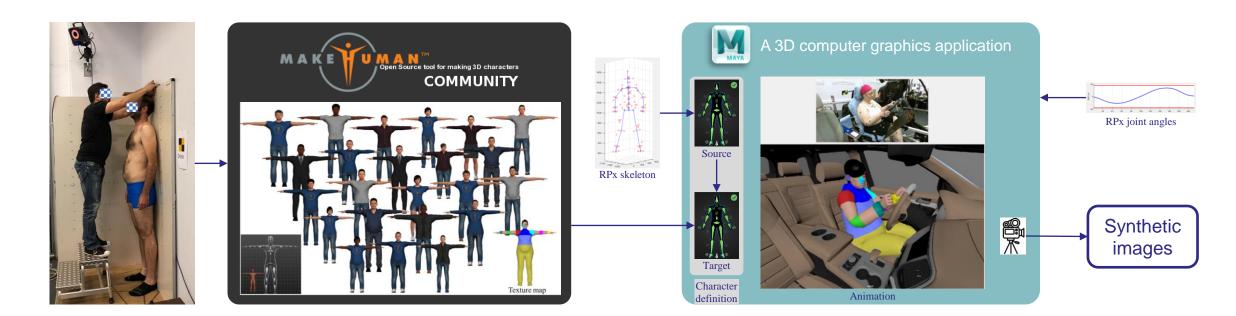


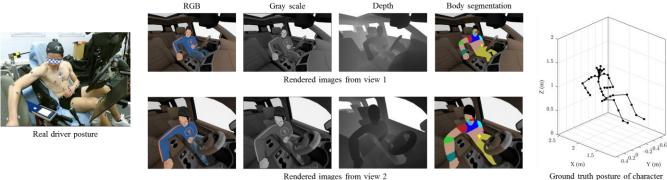


Data alignment after camera calibration and time synchronization

AutoConduct dataset

Data augmentation





ound truth postare of character

Synthetic data examples

AutoConduct dataset

Comparison with state-of-the-art



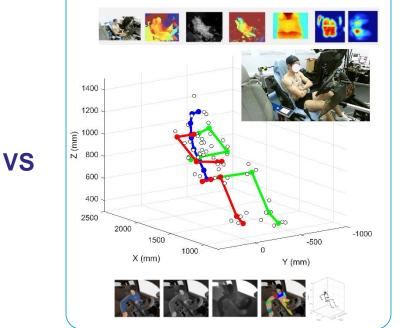
DD-Pose (Roth and Gavrila 2019), optical mocap for ground truth of head pose

Experiment data:

~130K frames of IR/RGB/Depth images, pressure data and 3D skeleton

Synthetic data:

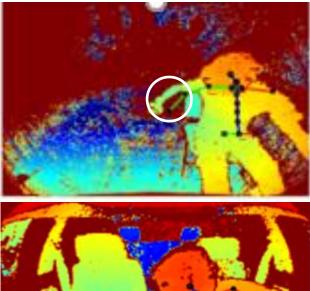
~12M frames of images, body segmentations and 3D skeleton

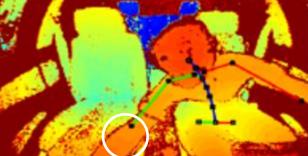


Driver anomaly detection dataset (Köpülü et al. 2021), no posture annotations

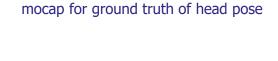
VS

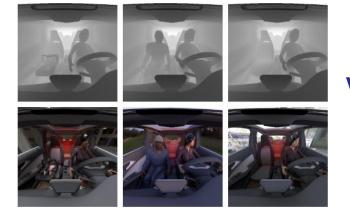
VS





InCar (Borges et al. 2021), IMU for ground truth of upper-body pose





TICam (Mirbach and El-sherif 2021), synthetic dataset

Posture estimation

Vision-based monitoring

3D skeleton (N = 129282)

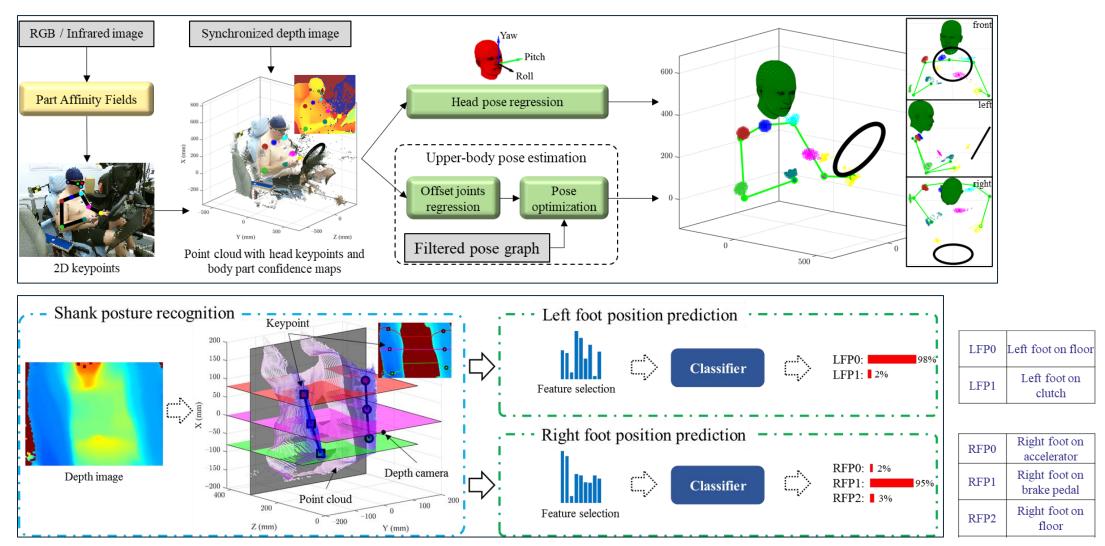
Average accuracy across seven body joints: 91%

Head pose (N = 129282)

 Mean errors of head orientation and position less than 11 deg and 2 cm in 96.3 % of all data samples

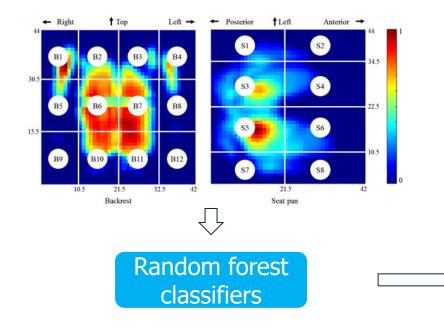
Feet positions (N = 5216 / 8024)

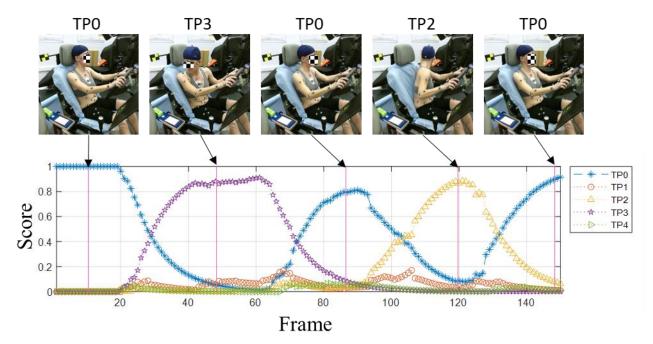
• Average classification accuracy of left and right foot is 93 % and 88 %, respectively



Posture estimation

Pressure measurement based monitoring





Continuous prediction of trunk postures by Leave-one-out cross-validation

Trunk posture classification (N = 3999)

- Average accuracy of 91 % from leave-one-out tests
- Feet position classifications (N = 5216 / 8024)
- Average classification accuracy of left/right foot positions: 93 % / 74 %

Overview of monitoring system

Experiment Test									
Measurement									
								، ا	
Initialized			Posture r	ecognition					
Content	1			5				Output	
MarkerSet								Head yaw-pitch-roll (deg))
RPxSkeleton	0.9 -							0 0	0
UbKeypoints	0.8 -							Head displacement (mm))
KinPointCloud								0 0	0
PmdPointCloud	0.7 -								
SegKinPCL								Trunk yaw-roll (deg)	-
SegPmdPcl	0.6 -							0	0
DSPointCloud								Trunk displacement (mm)	
 LbKeypoints 	0.5 -							0 0	0
✓ HeadMeshPrd	0.4 -							LHandStwDist (mm)	0
HeadMeshTru ReconizedPose	0.4							RHandStwDist (mm)	0
✓ OptimizedPose	0.3 -								
opunizedr0se								LFOnFloor (0-1)	0
Panel	0.2 -							LFOnClutch (0-1)	0
Driver 12	0.1 -							RFOnAcc (0-1)	0
Task 35								RFOnBrake (0-1)	0
CheckData 🥥	0 0.1	0.2 0.3	0.4 0).5 0.6	0.7	0.8 0.9	1	RFOnFloor (0-1)	0
Play Stop)								
Record	Frame 1	CaptureScre	en	CaptureFigure	•	FigureR	ecordin	g ScreenRecor	ding

Publications:

- Zhao, M., Beurier, G., Wang, H., & Wang, X. (2021). Exploration of Driver Posture Monitoring Using Pressure Sensors with Lower Resolution. Sensors, 21(10), 3346.
- Zhao, M., Beurier, G., Wang, H., & Wang, X. (2021). Driver posture monitoring in highly automated vehicles using pressure measurement. Traffic injury prevention, 22(4), 278-283.
- Zhao, M., Beurier, G., Wang, H., & Wang, X. (2020, August). Extraction of pressure features for predicting driver posture. In Proceedings of the 2020 IRCOBI conference, Munich, Germany (pp. 398-409).
- Zhao, M., Beurier, G., Wang, H., & Wang, X. (2020, May). Driver Posture Prediction Using Pressure Measurement and Deep Learning, In Proceedings of the 2020 IRCOBI (ASIA) conference, Beijing, China (pp. 102-105).
- Zhao, M., Beurier, G., Wang, H., & Wang, X. (2020). A Pipeline for Creating In-Vehicle Posture Database for Developing Driver Posture Monitoring Systems. In Proceedings of DHM2020, August 31-September 2, 2020 (Vol. 11, p. 187). IOS Press.
- Zhao, M., Beurier, G., Wang, H., & Wang, X. (2019, September). Detection of Driver Posture Change by Seat Pressure Measurement. In Proceedings of the 2019 IRCOBI conference, Florence, Italy (pp. 84-85).
- Zhao, M., Beurier, G., Wang, H., & Wang, X. (2018). In vehicle diver postural monitoring using a depth camera kinect (No. 2018-01-0505). SAE world congress 2018.

Future work

- Refinement of the proposed data augmentation pipeline
 - Driver-object interaction, sensor noise, vehicle models
 - Real driver motions will be made open access
- Improvement of proposed posture monitoring functions
 - Adaptation of more advanced algorithms for posture estimation
- Identification of critical postures based on posture monitoring & evaluation of their safety impact

Thank you for your attention

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